I am aware of the Berkeley Campus Code of Student Conduct and acknowledge that any academic misconduct on this exam will be reported to the Center for Student Conduct and may lead to a “F”-grade for the course. I am aware that Nick believes in retribution.

SIGN your name: __________________________________________

PRINT your class account login: cs61c-_____ and SID: ____________________

Your TA’s name: _________________________________________

**Number** of exam of person to your left: ____________  **Number** of exam of person to your right: ____________

You may consult four sheets of notes (each double-sided). You may not consult other notes, textbooks, etc. Calculators, computers, and other electronic devices are not permitted. Please write your answers in the spaces provided in the test.

You have 170 minutes. There are 13 questions, of varying credit (180 points total). The questions are of varying difficulty, so avoid spending too long on any one question. Parts of the exam will be graded automatically by scanning the **bubbles you fill in**, so please do your best to fill them in somewhat completely. Don’t worry—if something goes wrong with the scanning, you’ll have a chance to correct it during the regrade period.

**If you have a question, raise your hand, and when an instructor motions to you, come to them to ask the question.**
Problem 1  [MT1-1] Number Rep  (15 points)

Answer the following questions about number representation:

(a) Unsigned Base 4

(i) What is the range that a 4 digit unsigned base 4 number can represent? Write the bounds in decimal.

[__________, __________]

(ii) Convert 107_{10} to unsigned base 4.

(b) Signed Base 4

(i) Suppose we wanted to use a bias in order to represent negative numbers in base 4. If we are working with a 4 digit base 4 number, what should we choose as our bias? (Our bias should create equal amounts of negative and positive numbers for our range. If this is not possible, select a bias that will result in 1 more negative number than positive numbers). Express your answer in decimal.

Bias = - __________

(ii) Suppose rather than using a bias notation, we decide to do the following.

For each base 4 number, we will reserve the most significant digit to strictly be used as a sign bit. A digit value of 1 will indicate a negative number, and a digit value of 0 will indicate a positive number. Any other values will result in an invalid number. For instance:

0003_4 = +3   1003_4 = -3   2003_4 = Invalid

How many valid numbers can we represent with a 4 digit base 4 number using this scheme?

___________
(c) Given the following function in C:

```c
int shifter(int x, int shift) {
    if (x > 0) {
        return x >> shift;
    }
    return -1 * (x >> shift);
}
```

Given y is a negative integer, and that `shifter(y, 2)` outputs 4, what is the range of values of y?

hint: -8 >> 1 = -4

[________, ________]

(d) Implement the function `unsigned int base_convert(unsigned int num, unsigned int base)`. This function takes in non-negative integers `num` and `base`. You are guaranteed the following:
- `base` is an integer in the range [2, 10], no need to error check this
- `num` is comprised of ”digits” with a value between 0 and `base` - 1.
- All values fit inside an `unsigned int`.

Your job is to make it so the function returns the decimal value of `num` in base `base`. For example, `base_convert(30, 4)` would return 12, since 30₄ is 12₁₀. You may not use additional lines (do not put multiple lines on the same line via ;) but you may not need all the lines provided.

```c
unsigned int base_convert(unsigned int num, unsigned int base) {
    unsigned int value = ________, power = ________;
    while (________________________) {
        __________________________________________________________________________
        __________________________________________________________________________
        __________________________________________________________________________
        __________________________________________________________________________
        __________________________________________________________________________
    }
    return ______________;
}
```
Problem 2  \([MT1-2]\) Allocating an Order  

You are working on an e-commerce platform. Internally, orders are tracked through a struct called `order_t`. Your task is to write a function to allocate and initialize a new order. There’s a catch though! This platform must be robust to errors, so you are required to return an error value from this function in addition to the newly allocated order. The possible errors are defined for you as preprocessor directives.

(a) **Write new order**: Fill in the following code. Keep in mind the following requirements:

- You must return BAD_ARG if any inputs are invalid. The criteria for valid arguments is:
  - Unit price should be positive (no negative prices)
  - An order cannot be for more than MAX_ORDER items
  - Inputs must not cause your function to crash (or execute undefined behavior)
- You must return NO_MEM if there are any errors while allocating memory
- The tax rate is always initialized to TAX_RATE
- If your function returns OK, then new points to a valid struct that has been initialized with the provided values.

```c
typedef struct order {
    int quantity;
    double unit_price;
    double tax_rate;
} order_t;
```

```c
#define OK 0 /* Function executed correctly */
#define NO_MEM 1 /* Could not allocate memory for order */
#define BAD_ARG 2 /* An invalid argument was given */
```

```c
#define TAX_RATE 1.08
#define MAX_ORDER 100
```
/* Allocate and initialize a new order */
int new_order(order_t **new, int quantity, double unit_price) {
    /* Validate Arguments */

    /* Allocate "new" */

    /* Initialize "new" */

    return OK;
}

(b) Calling new_order: How would you use new_order() to allocate and initialize blue_monday with a quantity of 10 and a unit price of 3.50 in the example below?

order_t *blue_monday;
double total;
ret_t ret;

/* Fill in the arguments to new_order here */
ret = new_order( __________, __________, __________);

if (ret == OK) {
    printf("Total: %.lf\n",
            (new->unit_price * new->quantity * new->tax_rate));
} else {
    printf("Error\n");
}
Problem 3  [MT1-3] **RISCY**  

The function RISCY is known to take in two arguments, in \( a_0 \) and \( a_1 \).

(a) Fill in the blanks such that the code below executes properly and evokes \texttt{ecall} to print the value in register \( s_1 \). You may assume that \texttt{ecall} is a function that takes in two arguments \( a_0 \) and \( a_1 \). When \( a_0 \) is 1, it prints the value in register \( a_1 \).

RISCY: # Prologue

```
addi s0, x0, 1
add s1, x0, x0
```

Loop:  

```
addi a0, a0, 4
beq a1, s0, Ret
lw t1, -4(a0)
lw t2, 0(a0)
sub t1, t1, t2
bge t1, x0, Cont
neg t1, t1
Cont:  

```

```
blt t1, s1, next
mv s1, t1
next:  # print value in s1 for debugging purpose.

```

```
sw ________________
sw ________________
addi a0, x0, 1
mv a1, s1
ecall # ecall takes in a0(#1 for print) and a1(#register to print)
lw ________________
lw ________________
addi s0, s0, 1
j Loop
```

Ret  

```
mv a0, s1
# Epilogue
```

```
```

```
jr ra
```
(b) Convert the RISCV instruction \texttt{bge t1, x0, Cont} into machine code in \texttt{binary}. Assume \texttt{mv} and \texttt{neg} expands to one instruction. Express your answer in \texttt{binary} in the fields below.

\begin{tabular}{|c|c|c|c|c|}
\hline
\hline
\end{tabular}

(c) Translate \texttt{RISCY} into \texttt{C} code. You may or may not need all of the lines provided below. You can assume you have access to a new print function \texttt{printint} which takes in one argument, an integer, and prints it out:

\begin{verbatim}
void printint(int x);

RISCY(a0, a1) {

}
\end{verbatim}
Consider the following C code and assembly code:

```c
#include <stdio.h>

int main() {
    int i, sum = 0;
    for (i = 100; i != 0; i--)
        sum = sum + i * i;
    printf("The sum of sq from 100 .. 1 is %d\n", sum);
}
```

(a) Please fill in all lines in the above assembly code.
(b) How many pseudo-instructions are in the given assembly code? Count each occurrence as one pseudo-instruction.

- 4
- 5
- 6
- 7
- 8
- 9

(c) Create the symbol table and relocation table.

<table>
<thead>
<tr>
<th>Label</th>
<th>Address</th>
</tr>
</thead>
<tbody>
<tr>
<td>main</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Instruction</th>
<th>Address</th>
<th>Dependency</th>
</tr>
</thead>
<tbody>
<tr>
<td>la a0, str</td>
<td></td>
<td>str</td>
</tr>
</tbody>
</table>

(d) Replace the labels of PC-relative targets with their immediate values. What is the offset value of `bnez` at address `0x20`? Write your answer in decimal.

(e) The assembler takes two passes over the code to resolve PC-Relative target addresses.

- True
- False

(f) The absolute target addresses can be resolved at the assembler stage.

- True
- False

(g) Interpreted code should run faster than the compiled code.

- True
- False

(h) The compiler still needs to go through the linker stage even if we only have 1 source file to compile.

- True
- False
Problem 5  [MT2-1] Circuits and Timing  (9 points)

In this question, you will be working with a circuit that takes in three 8-bit inputs. For all parts, assume the delays below:

\[ t_{\text{clk-to-q}} = 3\text{ps}, \quad t_{\text{setup}} = 4\text{ps}, \quad t_{\text{shifter}} = 1\text{ps} \]
\[ t_{\text{adder}} = 5\text{ps}, \quad t_{\text{multiplier}} = 6\text{ps}, \quad t_{\text{subtractor}} = 4\text{ps} \]

Furthermore, assume that the inputs A, B, and C take on their new values exactly at the rising edge of every clock cycle and that all registers are initialized to zero.

Figure 2: Non-pipelined circuit

(a) What is the maximum possible hold time that still ensures the correctness of the non-pipelined circuit in figure 1? (Select only one)

- 1ps
- 3ps
- 4ps
- 5ps
- 7ps

(b) What is the minimum possible clock period that still ensures the correctness of the non-pipelined circuit in figure 1? You may assume that for this question that all flip-flops have a 0ps hold time requirement. (Select only one)

- 13ps
- 16ps
- 20ps
- 23ps
Now consider the pipelined version of the circuit (shown below). You will be using this circuit for the remaining part of the question. All delays remain the same. You may assume that the hold time is 0ps for the following questions.

![Pipelined circuit diagram](image)

**Figure 3: Pipelined circuit**

(c) What is the minimum clock period of the pipelined circuit in figure 2 that maintains the circuit’s correctness?

- 10ps
- 13ps
- 15ps
- 18ps

(d) How long does it take to compute the output for a given set of inputs? Assume the clock period is 11ps.

- 22ps
- 27ps
- 28ps
- 31ps
- 42ps
- 47ps
- 50ps
- other: ________
Problem 6  \([M2-2]\) Read and Write  \((15 \text{ points})\)

Recall in class we learned that we can optimize our CPU pipeline by having register writes then reads within the same cycle. Let’s call this implementation \textit{write-read}.

Consider a new implementation where register reads happen before register writes within the same cycle. Let’s call this implementation \textit{read-write}.

Now consider the following RISC-V code and answer the following questions about a 5-stage RISC-V pipeline. \textbf{Assume no forwarding and no branch prediction}. You are given that there needs to be at least one stall after line 4 for both implementations.

<p>| | | | | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
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<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>loop:</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>slli t0 a1 2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>or t2 a1 t1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>add t0 t0 a0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>4</td>
<td>lw t1 4(t0)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>beq t1 x0 loop</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>6</td>
<td>addi t2 t2 5</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7</td>
<td>sw t2 8(t0)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>8</td>
<td>add a0 t2 x0</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

(a) Consider the code above and the \textit{write-read} implementation. Which lines should be followed by a stall to guarantee correctness? (You are given that there needs to be at least one stall after line 4). For example, if an instruction on line A causes an instruction on line B to stall, bubble A.

- O 1
- O 2
- O 3
- ● 4
- O 5
- O 6
- O 7
- O 8

(b) Still considering the \textit{write-read} implementation, how many stalls are needed before the instruction on line 5 executes (do not include any stalls that occur after this point)?
(c) Now consider the **read-write** implementation, how many stalls are needed before the instruction on line 5 executes (do not include any stalls that occur after this point)?

_____

(d) Recall that you are given that there needs to be at least one stall after line 4 for both implementations. What type of hazard requires us to need at least one stall after line 4?

- Structural
- Control
- Data

(e) For **write-read**, how many stalls do we need between lines 4 and 5?

- 1
- 3
- 2
- 4

(f) For **read-write**, how many nops do we need between lines 4 and 5?

- 1
- 3
- 2
- 4

(g) If we decide to reorder instructions, which instruction is the best choice to replace a nop after line 4? Choose the line number of that instruction.

- 1
- 5
- 2
- 6
- 3
- 7
- 4
- None - no reordering needed
Problem 7  [M2-3] $$$ 
(18 points)

Assume we have a single L1 data cache having the following characteristics:
- 4 KiB cache size
- 16 byte blocks
- Direct Mapped

Assume the following piece of code is run in a 32-bit address space with sizeof(int) = 4:

```c
#define SIZE 8192 // 2^13

int ARRAY[SIZE]; // note: extra aligned: ((int) ARRAY) % 64 == 0

int main() {
    ARRAY[0] = ARRAY[4] + ARRAY[8]; // This happens before Loop 1
    for (int i = 0; i < SIZE - 16; i += 4) { // Loop 1
        ARRAY[i] += ARRAY[i + 4] + ARRAY[i + 8] + ARRAY[i + 12];
    }
    for (int i = SIZE - 1; i >= 0; i -= 32) { // Loop 2
        ARRAY[i] += 10;
    }
}
```

(a) Calculate the number of tag, index, and offset bits for this L1 cache.

   Tag: ________  Index: ________  Offset: ________

(b) Now, what is the hit rate for Loop 1 in the data cache? Assume that we start with a cold cache from the start of main().

   ________

(c) What is the hit rate for Loop 2 given that the cache is NOT reset after Loop 1?

   ________

(d) Assume that accessing memory takes 100 cycles, accessing data that is in the cache takes 5 cycles, Also assume for this part that Loop 1’s hit rate is 60% and Loop 2’s hit rate is 75%, which may or may not be the correct hit rates. What is the average memory access time (AMAT) in cycles for (Please reduce fractions):

   (i) Loop 1:

   ________
(ii) Loop 2:

(iii) Overall (an expression of REDUCED fractions is alright. You may use “T1” as the Loop 1 AMAT and “T2” as the Loop 2 AMAT in your calculation of this value):

Now we add in a L2 cache with the following characteristics:
- 16 KiB cache size
- 16 byte blocks
- Fully Associative

We re-run main() with cold L1 and L2 caches.

(e) What would be the local MISS rate of the L2 cache for Loop 1?

(f) What would be the local MISS rate of the L2 cache for Loop 2? Assume the caches are NOT reset after Loop 1. Also, don’t take into account the miss rate for Loop 1 when calculating Loop 2.
Problem 8  [M2-4] Datapath (10 points)

Recall the standard 5-stage, single cycle datapath contains stages for Instruction Fetch, Decode, Execute (ALU), Memory, and Write-back. Datapath designers are interested in reducing the phases necessary for execution such that instead of accessing both the Execute (ALU) phase and the Memory phase, instructions access either one or the other, but not both. This would create a 4-stage, single cycle datapath with the following stages: Instruction Fetch, Decode, Execute OR Memory, and Write-back.

<table>
<thead>
<tr>
<th>Instr Fetch</th>
<th>Instr Decode</th>
<th>Execute (ALU)</th>
<th>Memory</th>
<th>Write-back</th>
</tr>
</thead>
<tbody>
<tr>
<td>100ps</td>
<td>150ps</td>
<td>200ps</td>
<td>350ps</td>
<td>150ps</td>
</tr>
</tbody>
</table>

(a) Given the table above and the described datapath above, what is the time it takes for a single instruction that utilizes all stages to execute on the typical 5-stage, single cycle datapath?

(b) What is the time it takes for a single instruction that utilizes all stages to execute on the new 4-stage, single cycle datapath?

(c) If the designers go ahead with this modification, which instructions will NOT function correctly? Why? Please limit your answer to two sentences or less.

(d) Propose a program-level modification that will fix the issue. Do NOT propose a modification to the datapath. Please describe your modification in two sentences or less.
Problem 9  [F-1] Floating Point  (13 points)

IEEE 754-2008 introduces half precision, which is a binary floating-point representation that uses 16 bits: 1 sign bit, 5 exponent bits (with a bias of 15) and 11 significand bits. This format uses the same rules for special numbers that IEEE754 uses. Considering this half-precision floating point format, answer the following questions:

(a) For 16-bit half-precision floating point, how many different valid representations are there for NaN?

(b) What is the smallest non-infinite number it can represent? You can leave your answer as an expression.

(c) What is the largest non-infinite number it can represent? You can leave your answer as an expression.

(d) How many floating point numbers are in the interval [1, 2) (including 1 but excluding 2)?
Problem 10  \[F-2\] All Kinds of Parallelism  (18 points)

SIMD within a Register (SWAR) in RISCV: You are planning to obfuscate some messages before they get released to the world. Instead of doing it properly (via encryption), you want a simpler implementation. Your first idea is to add 1 to each character, e.g. turning “aabb” into “bbcc”? If we apply this method to “a quick brown fox jumps over the lazy dog”, it becomes “b!rvjdl!cspx0!gpy!kvnqt!pwfs!uif!mb{z!eph”!
It looks promising. And the implementation is plain and simple (both in C and RISCV):

```c
void obfuscate(char* d, size_t n) {
    for (int i = 0; i < n; i++) {
        d[i] += 1;
    }
}
```

```riscv
obfuscate:
    beqz a1, END
    add t0, x0, x0
LOOP:
    lb t1, 0(a0)
    addi t1, t1, 1
    sb t1, 0(a0)
    addi t0, t0, 1
    addi a0, a0, 1
    blt t0, a1, LOOP
END:
    ret
```

Things look great so far. Then you realize that you learned all kinds of crazy techniques to speedup a function in CS61C and this looks very similar to the many SIMD examples you have seen. Although RISCV does have SIMD instructions via a vector extension set, we want to implement our own version of RISCV SIMD. Our idea is to pack multiple characters into a single 32-bit integer. In fact, we do not even need to load and pack the data: four characters have the same width of an integer. Assume \(d\) is word aligned and that all input characters in the message are less than 254. Also assume \(n\) is the number of characters in the message and that register \(a0\) holds the value of \(d\) and register \(a1\) holds the value of \(n\).

(a) Complete the following implementation for a vectorized version of \texttt{obfuscate}:

```c
void obfuscate_vec(char* d, size_t n) {
    for (int i = 0; i < _________; _________) {
        *( (int*) (d + i) ) += INC;
    }
    /* handle tail cases */
    for (int i = _________; i < n; i++) {
        d[i] += 1;
    }
}
```

(b) Refer to the constant \texttt{INC} in the code above. What should the value of \texttt{INC} be such that \texttt{obfuscate_vec} works correctly? Write your answer in hexadecimal.

```
int INC = __________
```
(c) **Loop Unrolling**: You can optimize this procedure further! Loop unrolling is supposed to reduce the number of branch instructions. Complete the following:

```c
void obfuscate_vec_unroll(char* d, size_t n) {
    int i;
    for (i = 0; i < n; i++) {
        *((int*) (d + i)) += INC;
        *((int*) (d + i + 4)) += INC;
    }
    /* handle tail cases */
    for (int i = n; i < n; i++) {
        d[i] += 1;
    }
}
```

### obfuscate_vec_unrolled:

```assembly
beqz a1, END
add t2, a1, x0
srl t2, t2, __
sll t2, t2, __
beqz t2, TAIL
add t0, x0, x0
li t3, INC
LOOP_VEC:
    _________________
    add t1, t1, t3
    _________________
    addi a0, a0, __
    _________________
    addi t1, t1, __
    _________________
    addi a0, a0, __
    addi t0, t0, __
    blt t0, t2, LOOP_VEC
TAIL:
    add t0, t2, x0
LOOP_TAIL:
    lbu t1, 0(a0)
    addi t1, t1, 1
    sb t1, 0(a0)
    addi t0, t0, 1
    addi a0, a0, 1
    blt t0, a1, LOOP_TAIL
END:
    ret
```

(d) Given a message of length \( n \) characters, how many instructions are needed after loop unrolling? Express your answer in terms of \( n \), such as \( 3n + 4 \). In addition, what is the speed up when \( n \) is approaching infinity in comparison to the original non-optimized function `obfuscate`? Count pseudo-instructions as 1 instruction. You do not need to simplify your expressions.

- **# of Instructions:** ________________
- **Speedup:** __________
(e) You decide to further improve the code with thread parallelism using 4 threads! Fill in proper OpenMP directive to the blank below:

```c
void obfuscate_vec_unroll(char* d, size_t n) {
    // insert OpenMP directive here
    for (int i = 0; i < <code from part(c)>; <code from part(c)>)
    {
        *((int*) (d + i)) += INC;
        *((int*) (d + i + 4)) += INC;
    }
    /* handle tail cases */
    /* Location A */
    for (int i = <code from part(c)>; i < n; i++)
    {
        d[i] += 1;
    }
}
```

Someone tells you to add `#pragma omp parallel` at Location A in the code above. If you do this, which statement is true about the second for loop (the tail case)?

- O Always Incorrect
- O Always Correct, slower than serial
- Sometimes Correct
- O Always Correct, faster than serial

(f) Denote the speedup when n is approaching infinity of `obfuscate_vec_unroll` from part (d) as “S”. Suppose the overhead of running OpenMP is negligible in comparison to the rest of the code, and we can run four threads, what is the maximum speed up compared to the original non optimized function obfuscate?

(g) **WSC and Amdahl's Law**: The above program now runs in the cloud with many machines. obfuscation_vec_unroll is 90% of all execution (AFTER applying SWAR, unrolling, and OpenMP), and obfuscation_vec_unroll can be parallelized across machines.

(i) If we run `obfuscate_vec_unroll` on a cluster of 16 machines, what is the speedup? You may leave your answer as an expression.

(ii) What is the maximum possible speedup we can achieve if we have an unlimited number of machines?
Problem 11  [F-3] Pikachu Learns Spark  (16 points)
We are given the entire dataset of every Pokémon and we want to find the mean of all Pokémon id numbers by type. Some Pokémon have dual types so that Pokémon’s id number will contribute to the average total of both types. For example, Kyurem is both a dragon and an ice type so his id number will contribute to both type’s sum when considering the average. Fill in the blanks for the Python code below. Use the following Spark Python functions when necessary: map, flatMap, reduce, reduceByKey.

Sample input (pokemon_id, pokemon_name, pokemon_types):
646 Kyurem Dragon Ice
25 Pikachu Electric
257 Blaziken Fire Fighting

Sample output (Type, Number):
(Dragon, 587)
(Electric, 412)

def parseLine(line):
    tokens = line.split(" ")
    types = tokens[2:]
    results = []
    for type in types:
        results.append((__________, ____________________________))
    return results

def reduceFunc(v1, v2):
    return _______________________________

def average(k, v):
    return _______________________________

pokemonData = sc.parallelize(pokemon)
out = pokemonData.flatMap(__________________________)
      .________________________(________________________)
      .________________________(________________________)
Problem 12  

[F-4] Virtual Memory  

(20 points)

Demand paging (storing part of a process’ memory on disk) is yet another example of caching in computer systems. If we think of main memory as a cache for disk, what are the properties of this cache? Assume a machine with 64 bit addresses, 16KB pages, a 4-way fully associative TLB, and 8B words.

(a) Associativity?

○ Direct Mapped  ○ Fully Associative

○ N-Way Set Associative

(b) Block size:

(c) Address layout. Your answer should be of the form [N:M] where N is the bit number of the most significant bit of the field and N is the bit number of the least significant bit of the field. For example, if the tag consists of the first 4 least-significant bits, you should write [3:0]. If the field is not applicable to paging, you may write “N/A”.

Tag bits: ________  Index bits: ________  Offset bits: ________

(d) Write policy?

○ Write Through  ○ Write Back

(e) Allocation policy?

○ Write Allocate  ○ Write No Allocate

TLB Reach. We have written a strange and mysterious summation function. It uses a mystery constant called $T$. You may assume that $T$ is defined (but you don’t know what to) and that $\text{arr}$ will always have enough elements (the function will never access outside of $\text{arr}$). The function is run on a machine with the following properties:

- 64 bit addresses
- 4KiB pages
- 4 byte words
- 4GiB of main memory
- 1MiB fully-associative cache with 64 byte blocks
- 2 entry fully associative TLB
- 4 level page table with 8 byte entries
- The OS uses LRU when paging to disk
#define NITER 10*1024*1024
#define T ??? // see below

int MysterySum(int *arr) {
    int i = 0;
    int sum = 0;
    for(; i < NITER / 2; i++)
        int p = (i % T)*4096;
        int b = i % 4096;
        sum += arr[p + b];
}

/* Timer starts here*/
for(; i < NITER; i++) {
    int p = (i % T)*4096;
    int b = i % 4096;
    sum += arr[p + b];
}
/* Timer ends here */

return sum;
}

(f) **Performance of T**
Rank the following values of T based on how fast the second loop only executes (assuming the first loop has already ran). You should state whether pairs of values are < or =. For example, you should write 1 < 2 if T=1 causes the second loop to run strictly slower than T=2. Likewise, you could write 8=2 if 8 is about as fast as 2.

T = 1, 2, 3, 4

(g) **System Design**
What system parameter would you change in order to maximize system performance for T=27. You must mark only one of the following (pick the one with the largest performance gain):

- Address Size
- Page Size
- Word Size
- Main Memory Size
- Cache Capacity
- Cache Block Size
- TLB Capacity
- TLB Capacity
- TLB Associativity
- Page Table Depth
- Page Table Entry Size
(h) **Page Table Walk**

Given the list of virtual addresses, find the corresponding physical addresses. For each address, you must also note whether the access was a TLB hit, Page Table hit, or Page Fault (by writing yes/no for each). If the access is a page fault, you should leave the PPN and PA fields blank. Do not add this entry to the TLB.

Our virtual memory space has 16-byte pages and maintains a fully-associative, two-entry TLB with LRU replacement. The page table system is hierarchical and has two levels. The two most-significant bits of the VPN index the L1 table, and the two least-significant bits of the VPN index the L2 table.

<table>
<thead>
<tr>
<th>Virtual Address</th>
<th>Virtual Page Number</th>
<th>Physical Page Number</th>
<th>Physical Address</th>
<th>TLB Hit, Page Table Hit, Page Fault?</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x10</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x5C</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x39</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0x1F</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Page Table Base Register**

0x00

**Memory:**

<table>
<thead>
<tr>
<th>Address</th>
<th>Contents</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x00</td>
<td>0x20</td>
</tr>
<tr>
<td>0x04</td>
<td></td>
</tr>
<tr>
<td>0x08</td>
<td>0x10</td>
</tr>
<tr>
<td>0x0C</td>
<td></td>
</tr>
<tr>
<td>0x10</td>
<td></td>
</tr>
<tr>
<td>0x14</td>
<td>0x1C</td>
</tr>
<tr>
<td>0x18</td>
<td>0x28</td>
</tr>
<tr>
<td>0x1C</td>
<td></td>
</tr>
<tr>
<td>0x20</td>
<td></td>
</tr>
<tr>
<td>0x24</td>
<td>0x12</td>
</tr>
<tr>
<td>0x28</td>
<td>0x09</td>
</tr>
<tr>
<td>0x2C</td>
<td>0x5C</td>
</tr>
</tbody>
</table>

**TLB:**

<table>
<thead>
<tr>
<th>VPN</th>
<th>PPN</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Problem 13  \textit{[F-5] Potpourri}  
(8 points)

Answer the following questions

(a) You have a computer that, well, stinks. It goes down on average 6 times a day and it takes 1 hour to get working again. What is the current system’s availability?

- 0.5
- 0.6
- 0.7
- 0.8

(b) Assume you have the computer from part (a) when the manufacturer offers you a deal. \textbf{a:} A new computer that only crashes 4 times per day or \textbf{b:} support that can reduce the time to fix to 6 minutes. Which one should you choose?

- a
- b

(c) You have a processor that has a clock rate of 2GHz, a time to poll of 200 cycles for I/O, and you need to poll I/O at 100 Hz. If you use polling, what is the percentage of time you will need to spend polling?

- 1%
- 0.1%
- 0.01%
- 0.001%

(d) If the data comes in very infrequently do you want to use interrupts or polling? Why?

- interrupts
- polling
Figure 4: Good Luck And Don’t F*** It Up