Discussion 11

## 1 Data-Level Parallelism

The idea central to data level parallelism is vectorized calculation: applying operations to multiple items (which are part of a single vector) at the same time.

Below is a small selection of the available Intel intrinsic instructions. All of them perform operations using 128-bit registers. When we use an instruction with "epi32", we treat the register as a pack of 4 32-bit integers.

Function	Description
m128i	Datatype for a 128-bit vector.
m128i _mm_set1_epi32(int i)	Creates a vector with four signed 32-bit integers where every element is equal to i.
m128i _mm_loadu_si128(m128i *p)	Load 4 consecutive integers at memory address <b>p</b> into a 128-bit vector.
<pre>void _mm_storeu_si128(m128i *p,m128i a)</pre>	Stores vector <b>a</b> into memory address <b>p</b>
m128i _mm_add_epi32(m128i a,m128i b)	Returns a vector = $(a_0 + b_0, a_1 + b_1, a_2 + b_2, a_3 + b_3)$
m128i _mm_mullo_epi32(m128i a,m128i b)	Returns a vector = $(a_0 \times b_0, a_1 \times b_1, a_2 \times b_2, a_3 \times b_3).$
m128i _mm_and_si128(m128i a,m128i b)	Perform a bitwise AND of 128 bits in a and b, and return the result.
m128i _mm_cmpeq_epi32(m128i a,m128i b)	The ith element of the return vector will be set to 0xFFFFFFFF if the ith elements of a and b are equal, otherwise it'll be set to 0.

A longer list of Intel intrinsics can be found in the precheck worksheet!

1.1 SIMD-ize the following function, which returns the product of all of the elements in an array.

```
static int product_naive(int n, int *a) {
   int product = 1;
   for (int i = 0; i < n; i++) {
      product *= a[i];
   }
   return product;
}</pre>
```

Things to think about: When iterating through a loop and grabbing elements 4 at a time, how should we update our index for the next iteration? What if our array has a length that isn't a multiple of 4? What can we do to handle this tail case?

```
static int product_vectorized(int n, int *a) {
    int result[4];
    __m128i prod_v = _mm_set1_epi32(1);
    // Vectorized Loop
    for (int i = 0; i < n/4 * 4; i += 4) {
        prod_v = _mm_mullo_epi32(
                  prod_v,
                  _mm_loadu_si128((__m128i *) (a + i))
    }
    _mm_storeu_si128((__m128i *) result, prod_v);
    // Handle tail case
    for (int i = n/4 * 4; i < n; i++) {
        result[0] *= a[i];
    }
    return result[0] * result[1] * result[2] * result[3];
}
```

1.2 Recall that Amdahl's Law can be used to measure the maximum speedup that can be obtained through parallelization:

$$Speedup = \frac{1}{\left(1 - frac_{optimized}\right) + \frac{frac_{optimized}}{factor_{improvement}}}$$

Assume that we measure **product\_vectorized** to be 4x faster than its scalar version. We measure that 20% of our overall program is run serially while 80% is run in parallel. Calculate the performance increase gained from parallelizing our code.

$$\begin{aligned} \text{Speedup} &= \frac{1}{\left(1 - \text{frac}_{\text{optimized}}\right) + \frac{\text{frac}_{\text{optimized}}}{\text{factor}_{\text{improvement}}}} \\ &= \frac{1}{(1 - 0.80) + \frac{0.80}{4}} \\ &= \frac{1}{0.20 + 0.20} \\ &= \frac{1}{0.4} \\ &= 2.5 \text{x performance increase} \end{aligned}$$

1.3 Now we want to write a similar function that will only *add* elements given a certain condition. For example:

```
static int add20_naive(int n, int *a) {
   int sum = 0;
   for (int i = 0; i < n; i++) {
       if (a[i] == 20) {
        sum += a[i];
      }
   }
   return sum;
}
Fill in the function to use a vector mask to add elements only if they are equal to 20:
static int add20_vectorized(int n, int *a) {
   int result[4];
   // Fill sum_v with zeros
   __m128i sum_v = _____;
   int32_t twenty[4] = {20, 20, 20, 20};
   __m128i vec_twenty = _____;
   // Vectorized Loop
   for (int i = 0; i < _____; i += _____) {
       // Load array into vector
       __m128i vec_arr = _____;
       // Create vector mask
       __m128i vec_mask = _____;
       sum_v = _____;
   }
   _mm_storeu_si128(______);
   // Tail case...
   /* Omitted */
}
```

```
static int add20_vectorized(int n, int *a) {
    int result[4];
    _{m128i \text{ sum_v}} = _{mm_set1_epi32(0)};
    int32_t twenty[4] = {20, 20, 20, 20};
    __m128i vec_twenty = _mm_loadu_si128((__m128i *) twenty);
    // Vectorized Loop
    for (int i = 0; i < n/4 * 4; i += 4) {
        __m128i vec_arr = _mm_loadu_si128((__m128i *) (a + i)));
        __m128i vec_mask = _mm_cmpeq_epi32(vec_arr, vec_twenty);
        sum_v = _mm_add_epi32(
                  sum_v,
                  _mm_and_si128(vec_arr, vec_mask)
        );
    }
    _mm_storeu_si128((__m128i *) result, sum_v);
    // Tail case...
    /* Omitted */
}
```

# 2 Thread-Level Parallelism

For each question below, state whether the program is:

#### Always Correct, Sometimes Correct, or Always Incorrect

If the program is always correct, also state whether it is:

#### Faster than Serial or Slower than Serial

Assume the number of threads can be any integer greater than 1 and that no thread will complete in its entirety before another thread starts executing. arr is an int[] of length n.

```
// Set element i of arr to i
#pragma omp parallel
{
    for (int i = 0; i < n; i++)
        arr[i] = i;
}</pre>
```

- 1) Always Correct
- 2) Slower than Serial

The values will be correct at the end of the loop since each thread is writing the same values.

Note that there is no **for** directive, so every thread executes this loop in its entirety. The overhead of creating and managing threads will slow down the execution time to be slower than serial.

```
2.2 arr[0] = 0;

arr[1] = 1;

#pragma omp parallel for

for (int i = 2; i < n; i++)

arr[i] = arr[i-1] + arr[i - 2];
```

- 1) Sometimes Correct
- 2) Slower than Serial

Sometimes correct: the loop has dependencies from previous data, so each thread would have to wait for its previous dependency to finish which does not occur in this loop. However, there exists a thread ordering where they execute in such a way that they complete each iteration in sequential order.

Even if this happened, this would still be slower than serial due to the multithreading overhead required.

```
2.3 // Set all elements in arr to 0;
int i;
    #pragma omp parallel for
    for (i = 0; i < n; i++)
        arr[i] = 0;</pre>
```

- 1) Always Correct
- 2) Faster than Serial

The **for** directive automatically makes loop variables (such as the index) private, so this will work properly. The **for** directive splits up the iterations of the loop to optimize for efficiency, and there will be no data races.

```
2.4
    // Set element i of arr to i;
    int i;
    #pragma omp parallel for
    for (i = 0; i < n; i++) {
        *arr = i;
        arr++;
    }</pre>
```

- 1) Sometimes Correct
- 2) Slower than Serial

Because each thread shares the array pointer, there is a data race when incrementing the array pointer. If multiple threads are executed such that they all execute the first line, \*arr = i; before the second line, arr++;, they will clobber each other's outputs by overwriting what the other threads wrote in the same position. However, there is a thread execution order that will not encounter data races, though it will be slower than serial.

### 3 Critical Sections

3.1 Consider the following multithreaded code to compute the product over all elements of an array.

(a) What is wrong with this code?

The code has the shared variable **product**, which can cause data races when multiple threads access it simultaneously.

(b) Fix the code using **#pragma omp critical**. Where should you place the directive to create the critical section?

3.2 When added to a **#pragma omp parallel for** statement, the **reduction(operation: var)** directive creates and optimizes the critical section for a for loop, given a variable that should be in the critical section and the operation being performed on that variable. An example is given below.

```
// Assume arr has length n
int fast_sum(int *arr, int n) {
   int result = 0;
   #pragma omp parallel for reduction(+: result)
   for (int i = 0; i < n; i++) {
      result += arr[i];
   }
   return result;
}</pre>
```

Fix fast\_product by adding the reduction(operation: var) directive to the #pragma omp parallel for statement. Which variable should be in the critical section, and what is the operation being performed?

```
// Assume arr has length 8*n.
double fast_product(double *arr, int n) {
    double product = 1;
    for (int i = 0; i < n; i++) {
        double subproduct = arr[i*8]*arr[i*8+1]*arr[i*8+2]*arr[i*8+3]
                        * arr[i*8+4]*arr[i*8+5]*arr[i*8+6]*arr[i*8+7];
        product *= subproduct;
    }
    return product;
}
double fast_product(double *arr, int n) {
    double product = 1;
    #pragma omp parallel for reduction (*:product)
    for (int i = 0; i < n; i++) {
        double subproduct = arr[i*8]*arr[i*8+1]*arr[i*8+2]*arr[i*8+3]
                         * arr[i*8+4]*arr[i*8+5]*arr[i*8+6]*arr[i*8+7];
        product *= subproduct;
    }
    return product;
}
```

3.3 Take a look at the following code which is run with two threads:

```
#define N 5

void func() {
  int A[N] = {1, 2, 3, 4, 5};
  int x = 0;
  #pragma omp parallel
  {
    for (int i = 0; i < N; i += 1) {
        x += A[i];
        A[i] = 0;
    }
}</pre>
```

What are the maximum and minimum values that **x** can have at the end of **func**?

Each of the 2 threads will independently:

- Read value from X
- · Read value from A
- Add value to x
- Zero out value in A
- Do the loop for 5 iterations each

Maximum: x = 30 – if thread 1 reads from x, reads from the array, and adds to x, and then thread 2 reads from the new x, reads from the array, and adds to x before the array entry gets zeroed, then x will have the value of x += A[i] + A[i].

Minimum: x = 0 – thread 2 reads from x getting the value x = 0 but halts and waits for thread 1 to completely finish (setting all array entries to 0). When thread 2 resumes execution, it will add its current value for x to a zeroed A[i] which will be 0 + 0 = 0 at all iterations of the loop.

# 4 OpenMProgramming

Consider the following C function:

```
#define ARRAY_LEN 1000

void mystery(int32_t *A, int32_t *B, int32_t *C) {
  for (int i = 0; i < ARRAY_LEN; i += 1) {
    C[i] = A[i] - B[i];
  }
}</pre>
```

4.1 Manually rewrite the loop to split the work equally across N different threads.

```
#define ARRAY_LEN 1000

void mystery(int32_t *A, int32_t *B, int32_t *C) {
    #pragma omp parallel
    {
        int N = OMP_NUM_THREADS;
        int tid = omp_get_thread_num();

        for (int i = tid; i < ARRAY_LEN; i += N) {
            C[i] = A[i] - B[i];
        }
    }
}</pre>
```

4.2 Now, split the work across N threads using a **#pragma** directive:

```
#define ARRAY_LEN 1000

void mystery(int32_t *A, int32_t *B, int32_t *C) {
    #pragma omp parallel for
    for (int i = 0; i < ARRAY_LEN; i += 1) {
        C[i] = A[i] - B[i];
    }
}</pre>
```

Instead of saving the product to an array C, we now want to XOR the subtraction of all the elements of A and B.

```
int mystery(int32_t *A, int32_t *B) {
  int result = 0;
  #pragma omp parallel for
  for (int i = 0; i < ARRAY_LEN; i += 1) {
    result ^= A[i] - B[i];
  }
  return result;
}</pre>
```

#define ARRAY\_LEN 1000

What is the issue with the above implementation and how can we fix it?

There is a race condition for the **result** variable.

4.4 Solve the problem above in two different methods using OpenMP:

```
int mystery(int32_t *A, int32_t *B) {
      int result = 0;
      #pragma omp parallel for
      for (int i = 0; i < ARRAY_LEN; i += 1) {</pre>
        #pragma omp critical
        result ^= A[i] - B[i];
      }
      return result;
    }
(b)
    int mystery(int32_t *A, int32_t *B) {
      int result = 0;
      #pragma omp parallel for reduction(^:result)
      for (int i = 0; i < ARRAY_LEN; i += 1) {</pre>
        result ^= A[i] - B[i];
      }
      return result;
    }
```

Assume we run the above mystery function with 8 threads. The parallel portion accounts for 80% of the program and is 8x as fast as the naive implementation. Use Amdahl's Law to calculate the speedup of the full program where

$$\begin{split} \text{Speedup} &= \frac{1}{\left(1 - \text{frac}_{\text{optimized}}\right) + \frac{\text{frac}_{\text{optimized}}}{\text{factor}_{\text{improvement}}}} \\ \text{Speedup} &= \frac{1}{\left(1 - \text{frac}_{\text{optimized}}\right) + \frac{\text{frac}_{\text{optimized}}}{\text{factor}_{\text{improvement}}}} \\ &= \frac{1}{(1 - 0.8) + \frac{0.8}{8}} \\ &= \frac{1}{0.2 + 0.1} \\ &= 3.333x \text{ speedup!} \end{split}$$

4.6 What is the maximum speedup we can achieve if we use unlimited threads in the parallel section for an infinite performance increase? Assume the parallel portion still accounts for 80% of our program.

$$\begin{split} \text{Speedup} &= \frac{1}{\left(1 - \text{frac}_{\text{optimized}}\right) + \frac{\text{frac}_{\text{optimized}}}{\text{factor}_{\text{improvement}}}} \\ &= \frac{1}{(1 - 0.8) + \frac{0.8}{9999999...}} \\ &= \frac{1}{0.2} \\ &= 5\text{x maximum speedup!} \end{split}$$

4.7 What does the above result tell you about using parallelism to optimize programs?

Programs can only be as fast as their serial portion.